



SESAME's Control System Status

Fall 2014 EPICS Collaboration meeting 22/10/2014

Presented by:

Ibrahim Saleh

Fall 2014 EPICS Collaboration Meeting



What is SESAME?

- SESAME (Synchrotron-light for Experimental Science and Applications in the Middle East)
- First international 3rd generation Synchrotron Light Source in the Middle East region
- Under construction near Amman (Jordan)
- Expected to become operational in 2016

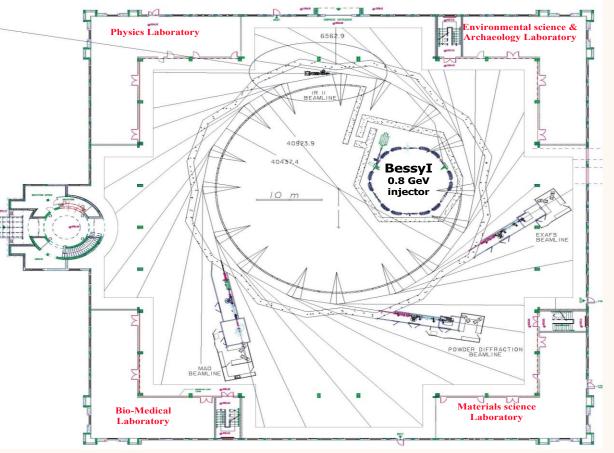




SESAME-Members: Bahrain, Cyprus, Egypt, Israel, Iran, Jordan, Pakistan, Palestine, Turkey







Energy; 2.5 GeV Circumference; 133m Emittance; 26 nm-rad 12 Insertion Devices 13 Bend Magnet beam lines Maximum beam line length; 37m

12 straight sections are available for IDs with lengths up to 3.9 m

- Space for future full energy injector in the main ring tunnel
- > SESAME's injector (Microtron and Booster Ring) have been commissioned
- Commissioning of the storage ring is expected in 2016



Control Group







Ibrahim Saleh

Abdallah Ismail

Yazan Dabain



Control System Status

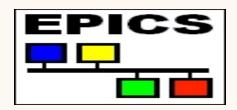
Outline:

- > Overview
- Infrastructure
- Booster Control System
- IOCs Development
- Clients Development
- Archive System
- Alarm Handler
- Future Work



Overview

- Control System Implementation uses (EPICS) base 3.14.12
- Clients are implemented using a custom build of Control System Studio (CSS) based on V.3.16
- Servers are implemented as EPICS
 Input/Output Controllers (IOCs)
 - Soft IOCs (Linux Machines)
 - Hard IOCs (Libera, VME)











Overview

- Siemens S7 PLCs are used for the machine interlocks
- Allen Bradley PLC is used for the Personal Safety System (PSS).
- Git version Control System is used to track development & documentation
- Development and administration platforms use Scientific Linux 6.4









Infrastructure

- Twelve virtual servers reserved to run the following: IOCs, Archiver, Alarm Handler, GIT Repository, Elog server, Bugzilla, Wiki server and File transfer servers
- > All workstations and servers have been migrated to Scientific Linux 6.4
- All clients, servers, and controllers are connected to an isolated machine network.
- A version control system is used to track development using GIT. Separate repositories exist for: IOCs, clients, documentation, required software packages and CSS



Infrastructure

- Issues tracking (including bugs and tasks) is done using Bugzilla.
 Any group may submit a bug/task for any other group
- ELOG is used by operators to write information during the commissioning, which makes it easy for other people to access this information through a Web interface, browse entries, search, download files, and optionally add, update, delete or comment on entries
- MediaWiki server has been recently installed. Documents will be transferred to this wiki to enable easy access



Booster Control System



General Architecture



Booster Ring



Booster Control System

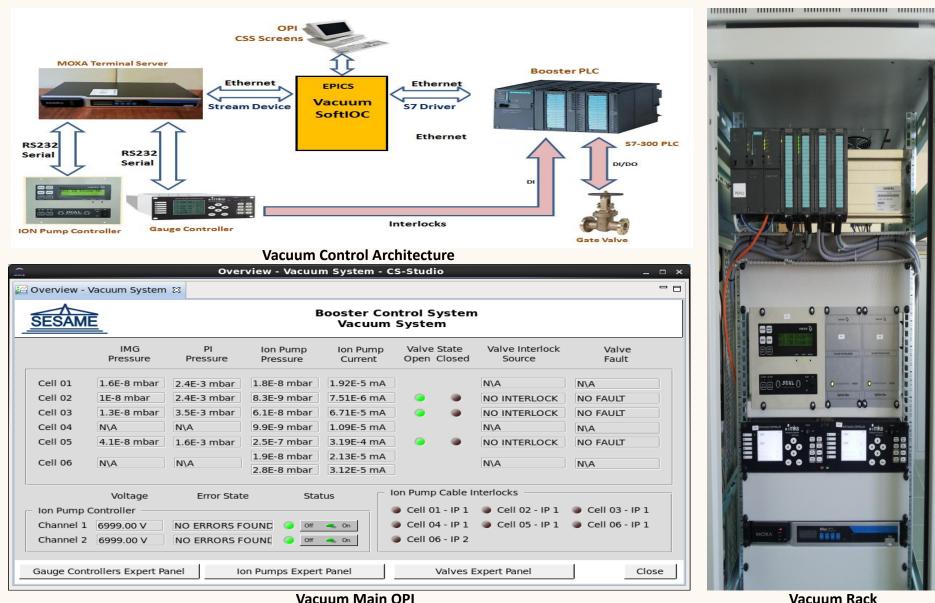
	Vacuum
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- > Power Supplies
- ≻ RF
- Diagnostics
- Cooling
- > Timing
- > PSS

💭 🛛 Main Menu -	CS-Studio _ 🗆 ×
🔛 Main Menu 🛛	
SESAME M	ain Control System
Microtron Control System	
Operation	Actuating Motors
Analog Signals	Trim Coils
Main Magnet PS	
Transfer Line (1) Control Sys	stem
Power Supplies	Vacuum
Booster Control System	
Vacuum	RF
Power Supplies	Diagnostics
Cooling	Timing
Profiles	
/home/control/nfs/burt/ram	ping-fu 🚰 Use Current Time
Save Profile	Restore Profile
Tools	
Archiver	Alarm Handler
Window Profiles	
Save Profile	Restore Profile
Machines Manager	Close



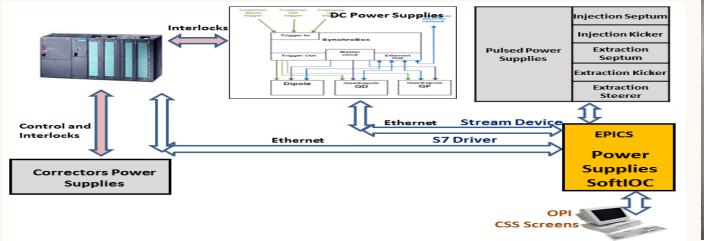
Booster Control System - Vacuum





Vacuum Rack

SESAME Booster Control System – Power Supplies





Power Supplies Control Architecture

		Ονε	erview - Power Su	pplies - CS-Stu	dio				
Overview - Power Su	upplies 🛛								-
SESAME				ster Control S er Supply - Ov					
	State	Operation Mode	Instantaneous Current	Instantaneous Current (A)	Trigger Mask	L/R I	Mode	Interlock	
DC Power Supplies									
BM	PULSE ON	WAVEFORM	145.45 A	24.50	107374006			Details	
QF	PULSE ON	WAVEFORM	83.79 A	2.65	107374005			Details	
QD	PULSE ON	WAVEFORM	77.78 A	2.26	107374005	5 p: REMOT	E	Details	
S-Box	IDLE	N∖A	N\A	N\A	N\A	N\A	۲	Details	
	Current	Current (A)	Remote Mode PS Inv		Current (Get)	Voltage	Voltage (V)	Trigger Enable	
Booster Correctors –				Pulsed Injection	Power Supplies				
BOC01-PS-CR1	- 0.00 A	- 0.00		Septum	7.7932E-4 A	690.02 V	690.00	Off 🤜	On
BOC02-PS-CR1	- 0.01 A	- 0.00	- o l	Kicker	-2.3148E-5 A	340.06 V	340.00	Off 🗨	On
BOC03-PS-CR1	- 0.14 A	- 0.15	T 💿 💿 🗌						
BOC04-PS-CR1	+ 0.00 A	+ 0.00							
BOC05-PS-CR1	+ 0.01 A	+ 0.00							
BOC06-PS-CR1	+ 0.26 A	+ 0.25							
- DOCUDA D-CIVI	. 0.20 A	1 0.25							
DC Power Supplies	Panel Co	rrector Power Suppli	es Panel Pulse	d Power Supplies F	anel	Demagnetiz	ation		Close

DC Power Supplies

-

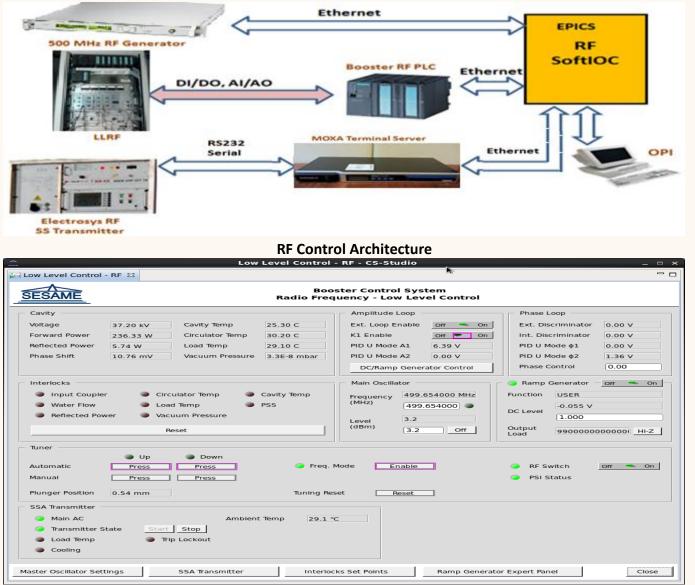


Power Supplies PLC

Power Supplies Main OPI



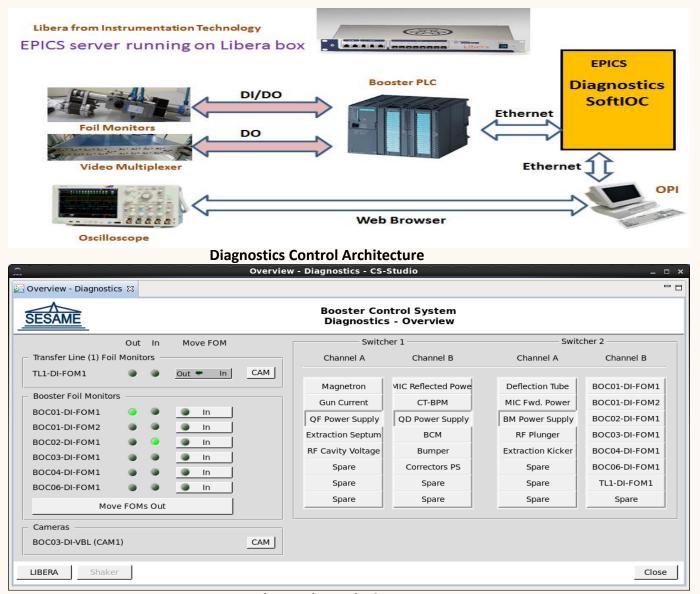
Booster Control System - RF



LLRF Rack

RF Main OPI



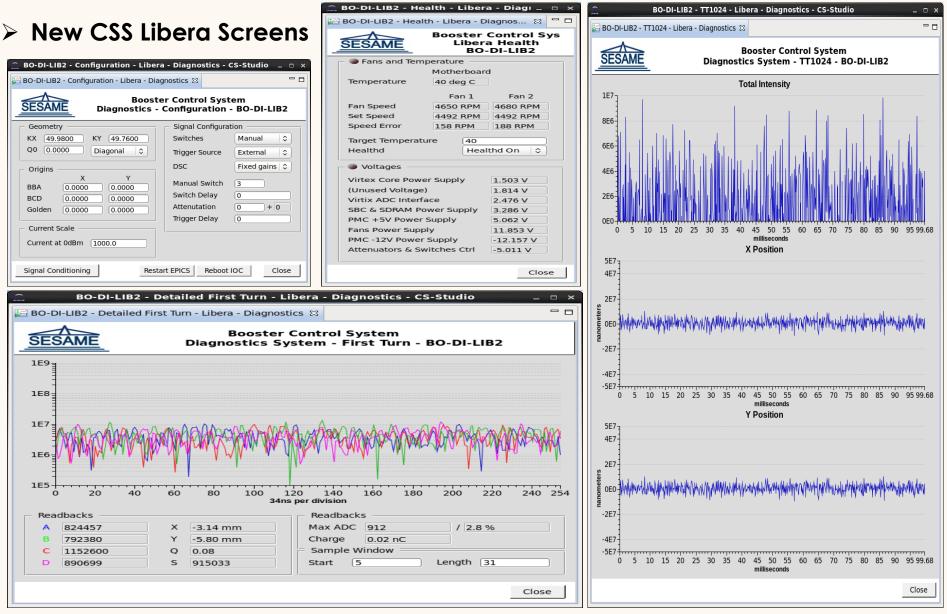




Diagnostics Rack

Diagnostics Main OPI

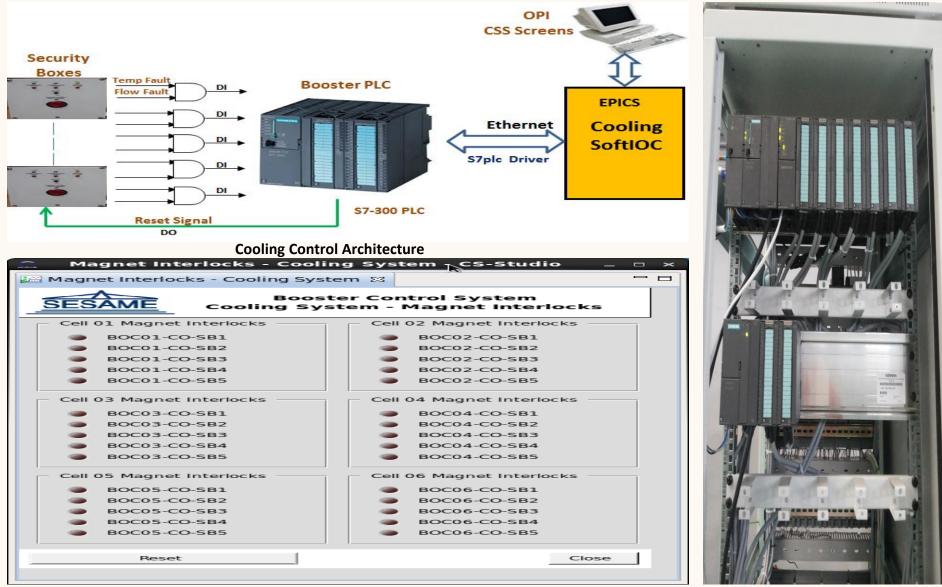
BOOSTER CONTROL System - Diagnostics



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Booster Control System - Cooling



Cooling Main OPI

Cooling Rack



Timing Control System

	9	Ti	ming System - O	CS-Stu	ıdio	_ = ×				
	🚰 Timing System	83			- N	- 8				
VME Crate from PSI	SESAME	AME Booster Control System Timing System								
- One EVG card		Local Delay	Pulse Width		Event Number					
- One EVR card	Event Receiver									
	RF-AMP	66820.019 μs	60.000	μs	16	Disabled Enabled				
	BM	86710.019 μs	2.000	μs	16	Disabled Enabled				
1 · Casar	INJ-SEPT	0.000 µs	2.000	μs	17	Disabled Enabled				
•12V	INJ-KICK	172.260 μs	4.000	μs	17	Disabled Enabled				
•12V L-164	MICROTRON	32.000 µs	30.000	μs	18	Disabled Enabled				
	BPM	40.000 μs	2.000	μs	19	Disabled Enabled				
	TL1-DI-CAM1	0.330 µs	6.000	μs	20	Disabled Enabled				
	BOC03-DI-CAI	200000.000 μs	6.000	μs	20	Disabled Enabled				
	QF	86820.019 μs	2.000	μs	16	Disabled Enabled				
	QD	86820.019 μs	2.000	μs	16	Disabled Enabled				
C C C C C C C C C C C C C C C C C C C	SPECTRUM	5.000 μs	2.000	μs	18	Disabled Enabled				
		Local Delay			Event Number	Quick Control				
	Event Generate	or				Enable/disable DC power supplies				
	START	0.000 µs	384	ns	16	trigger				
	INJ	117118.252 μs	117118208	ns	17	Disable Enable				
	PREINJO	117242.252 μs	117242240	ns	18					
	BPM	117243.252 μs	117243136	ns	19					
	CAM	117243.252 μs	117243264	ns	20					
	 Frequencies Co 	ntrol								
	System Freq.	1.000 Hz	1	Hz	•					
			# of Pulses	112						
0	Microtron Freq.	1.00 Hz	# of Pulses		pulses					
	Update System	Frequency				Close				
		requency				Ciose				

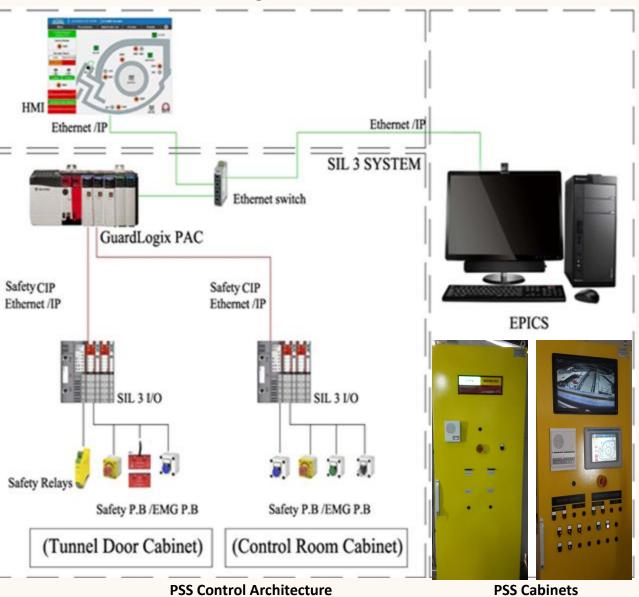
Timing Hardware

Timing Main OPI



PSS Control System

- EtherIP driver/device support module interfaces Allen Bradley Guard Logix safety PLC via Ethernet to EPICS IOC
- The PSS IOC monitors the safety interlocks and showing them on the CSS





IOC Manager

- Enable/Disable the IOCs
- Synchronize IOCs with the version control repository
- Monitor the uptime, free RAM, free space and the average load of the IOCs
- Manage the development machines and other infrastructure servers.

2				Machine Manag	jer - CS-Studio								_ ¤ ×
🖉 Machine Manage	r 🛙												- 0
SESAME	Main Control System Machine Control												
	Usemame	IOC Uptime	Free RAM	Free Space	Average Load	ļ	Appli	cation		Ena	ble	Sync	
– Virtual Machine	s ———												
SERVER-RS0	control	24d00h44m	664.1 MB	40.95 GB	0.00	booster	\$	vacuum 🗘	0	Off	🤜 On	0	Update
SERVER-RS1	control	07d18h11m	633.4 MB	39.96 GB	0.00	booster	\$	power 🗘	0	Off	🤜 On	0	Update
SERVER-RS2	control	01d23h05m	354.0 MB	39.07 GB	0.00	booster	÷	rf 🔷	0	Off	🤜 On	0	Update
SERVER-RS3	control	02d19h19m	337.6 MB	39.73 GB	0.00	booster	\$	diagnostic 🗘	0	Off	🤜 On	0	Update
SERVER-RS4	control	24d00h44m	381.8 MB	40.94 GB	0.00	booster	\$	cooling 0	0	Off	🤜 On	0	Update
SERVER-RS5	control	07d17h42m	431.2 MB	40.96 GB	0.00	pss	\$	pss 🗘	0	Off	🤜 On	0	Update
SERVER-RS6	control	24d00h44m	426.8 MB	40.99 GB	0.00	microtron	\$	microtron 🗘	0	Off	🤜 On	0	Update
SERVER-RS7	control	02d00h42m	286.3 MB	39.83 GB	0.00	tl1	Ŷ	tl1 \$	0	Off	🤜 On	0	Update
– Service Area –													
								L		_			Lange 1
SERVICE-WS2	control	00d00h00m	9.4 MB	4.30 GB	0.00		¢	\$		Off	🕈 On	۳	Update
- Control Room M	lachines —												
CONTROL-OP0	control	00d00h00m	1189.0 MB	445.81 GB	0.47		\$	\$		Off	🗭 On		Update
CONTROL-OP1		00d00h00m	277.9 MB	449.28 GB	0.18		\$	\$		Off		ă.	Update
							•			_			
Lab Machines													
LAB-WS1	control	00d00h00m	927.3 MB	60.69 GB	0.00		\$	\$		Off	🖻 On	0	Update
LAB-WS2	control	00d00h00m	77.4 MB	133.12 GB	0.48		¢	\$	0	Off	🕈 On	0	Update
Infractructure													
- Infrastructure -													
SERVER-IS1	control	00d00h00m	33.0 MB	74.76 GB	0.00		¢	¢		Off	🕈 On		Update
													Close



Basler GIGE Camera Driver

- Ace acA1300-30gm GigE camera, no drivers available
- Purpose: Speed up scientific analysis, system integration Needed image, gain, exposure, ROI, and trigger control
- Record types: Bi, bo, longin, longout, waveform
- Device support: Asynchronous processing (I/O thread)
- Driver support: One thread per device, message passing
- Device driver: Shared C++ libraries from Basler



Basler GIGE Camera



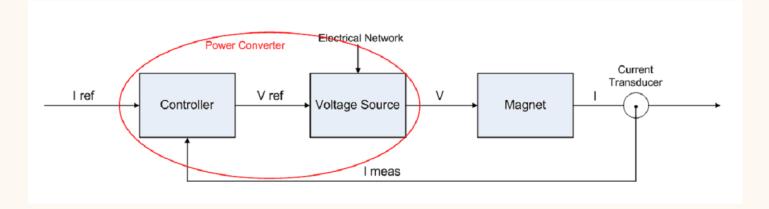
Beam Image





Storage Ring Power Supplies Control System

- Current controlled power supplies have 2 loops; a fast voltage feedback loop and slow current feedback loop
- We bought a power supply which already contains the voltage feedback loop from industry (Voltage Source)
- The current feedback loop is then implemented using PSI power supplies controllers

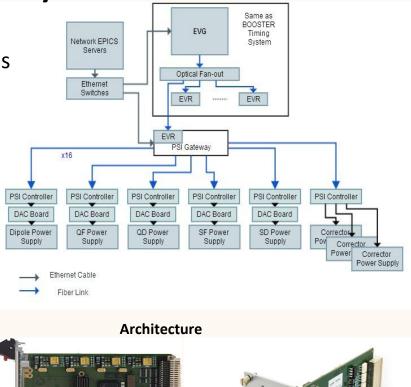






Storage Ring Power Supplies Control System

- Control room communicates with gateways
- Gateway distributes commands to power supplies
 - **Reference** current
 - Waveforms
 - Triggering and synchronization
 - Fast orbit feedback
 - Parameterization
 - Firmware upgrades
- Power supply drives magnet
 - Triggering and tracking repsonse and
 - jitter < 100us
 - Over damped response
 - Settling time within 50ppm < 1ms
 - Phase margin > 60







Gateway

Controller24

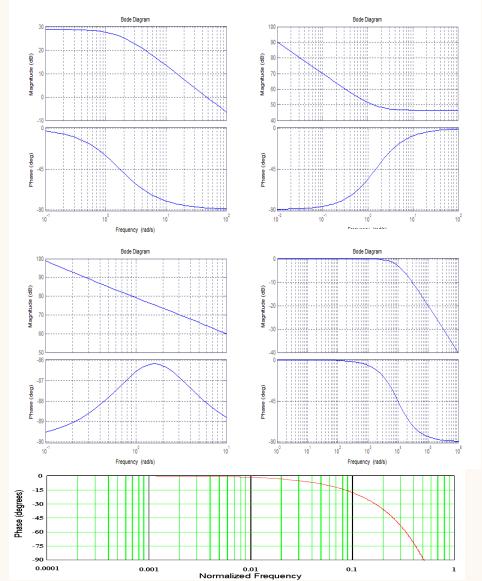




Storage Ring Power Supplies Control System

- Controller design requirements
 - Overdamped response
 - Settling time < 1ms
 - Error band < 50ppm
 - Phase margin > 60
- PI Controller design procedure
 - Gp has dominant real pole due to magnet
 - Place zero to cancel dominant pole
 - Place pole at origin
 - Close the loop and set bandwidth
 - Select sampling rate to achieve phase margin
- Design equations:
 - Ki = Wp, 10tau = 1ms, BW = 1/tau,

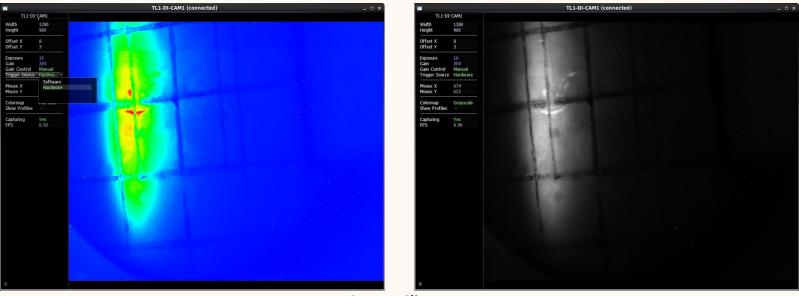
Kp = L.BW, Fs > 4Fc Fall 2014 EPICS Collaboration Meeting





Basler GIGE Camera Client

- Uses EPICS client framework
- Built using C, OpenGL, SDL and AntTweakBar
- Provide an interface to control basler camera parameters such as: image size, offset, gain, exposure and trigger source
- Provides different color maps



Camera Client

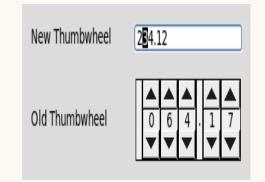


SESAME CSS

- A custom SESAME build based on CSS v3.16



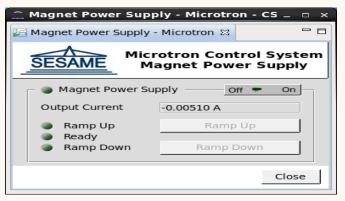
- Adding archiver and alarm handler to be integrated with the CSS
- CSS starts in run-time mode directly without showing the eclipse development windows.
- Adding a thumbwheel function to the input box widget to provide a compact fine-tunable control to PVs





SESAME CSS

- Showing screen names on windows title bar



- Only one instance of identical windows allowed at a time
- Adding window profiles saving and loading to arrange the CSS workspace

Window Profiles	
Operation	0
Save Profile	Restore Profile



SESAME CSS Standards

All CSS screens follow a standard interface to ease and clarify usage for operators

Examples:

- Color coding LEDs: green LEDs show on/off state, red LEDs show interlock signals, yellow LEDs used for limit switches



3.00

- All reading fields have a gray background, while write-able fields have a white background

 Pressure
 Set Point

 Set Point
 Set Point

1.8E-8 mbar

- Tables are used throughout to monitor and control the devices



- BURT (Back Up and Restore Tool)
 - Saves machine state and restores it later
 - Uses a network file system to provide saved profiles on all operator's computers

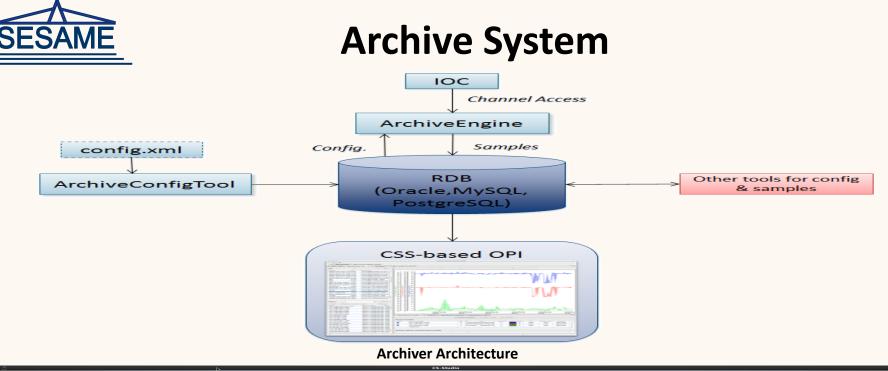
Profiles								
/home/control/nfs/burt/ramping-fu 彦 Use Current Time								
Save Profile	Re	estore Profile						
		,						

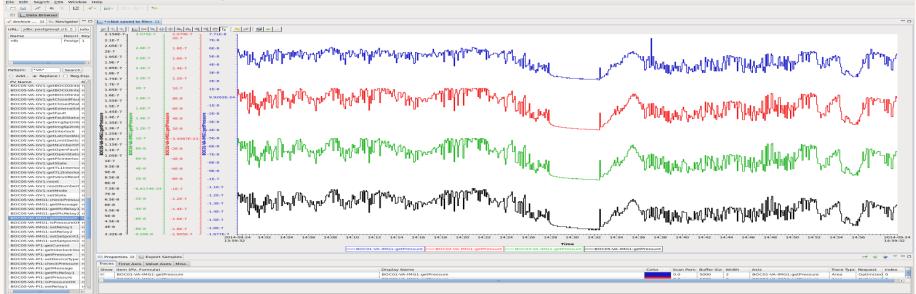
📸 Wed28-nice-beam-at-extract.snp (nfs) - gedit	×
<u>F</u> ile <u>E</u> dit <u>V</u> iew <u>S</u> earch <u>T</u> ools <u>D</u> ocuments <u>H</u> elp	
哈 🔤 Open 🗸 🖄 Save 📇 🏐 Undo ऌ 💥 🖫 💼 🌮	9. 👧
📄 Wed28-nice-beam-at-extract.snp 🗶	
SDDS1	
¶meter name=TimeStamp, type=string, fixed_value="Wed May 28 19:37:45 2014	
", &end	
¶meter name=LoginID, type=string, fixed_value="control ()", &e	and
¶meter name=EffectiveUID, type=string, fixed_value=504, &end	
<pre>&parameter name=GroupID, type=string, fixed_value=504, &end &parameter name=BurtKeywords, type=string, fixed_value="", &end</pre>	
¶meter name=BurtComments, type=string, fixed_value="", &end	
¶meter name=SnapType, type=string, fixed_value=Absolute, &end	
&column name=ControlName, type=string, &end	
&column name=ControlType, type=string, &end &column name=Lineage, type=string, &end	
&column name=BackupMsg, type=string, &end	
&column name=RestoreMsg, type=string, &end	
&column name=ControlMode, type=string, &end	
&column name=Count, type=long, &end &column name=ValueString, type=string, &end	
Adata mode=ascii, &end	
! page number 1	
33	
MI-MA-TC1:reversePolarity1 pv 1 "\"reverse off\"" MI-MA-TC1:I1-set pv 1 2.0000000000000000e-01	
MI-MA-TC1:reversePolarity2 pv 1 "\"reverse On\""	
MI-MA-TC1:I2-set pv 1 0.000000000000000000000000000	
MI-MA-TC2:reversePolarity1 pv 1 "\"reverse off\"" MI-MA-TC2:I1-set pv 1 1.20000000000000000000000000000000000	
MI-MA-TC2:reversePolarity2 pv 1 "\"reverse On\""	
MI-MA-TC2:I2-set pv 1 0.00000000000000e+00	
TL1-MA-CR3:reversePolarity1 pv 1 "\"reverse off\""	
TL1-MA-CR3:I1-set pv 1 0.000000000000000000+00 TL1-MA-CR3:reversePolarity2 pv 1 "\"reverse off\""	
TL1-MA-CR3:12-set pv 1 0.0000000000000000000	
TL1-MA-CR4:reversePolarity1 pv 1 "\"reverse off\""	
TL1-MA-CR4:II-set pv 1 4.80000000000000e-01	
TL1-MA-CR4:reversePolarity2 pv 1 "\"reverse off\"" TL1-MA-CR4:I2-set pv 1 5.3000000000000000e-01	
TL1-MA-CR5:reversePolarity1 pv 1 "\"reverse On\""	
TL1-MA-CR5:I1-set pv 1 1.50000000000000000000000000000	
TL1-MA-CR5:reversePolarity2 pv 1 "\"reverse off\"" TL1-MA-CR5:I2-set pv 1 0.000000000000000e+00	
TL1-MA-CR5:12-Set pv 1 0.000000000000000000000000000	
TL1-MA-CR6:I1-set pv 1 2.980000000000000e+00	
TL1-MA-CR6:reversePolarity2 pv 1 "\"reverse On\""	
TL1-MA-CR6:I2-set pv 1 1.40000000000000000000000000000000000	
TL1-MA-TRP1-PS1:setCurrent pv 1 2.1800000000000000e+00	
TL1-MA-TRP2-PS1:setCurrent pv 1 4.80000000000000000000	
TL1-MA-TRP2-P52:setCurrent pv 1 1.01000000000000e+00	
BO-PS-BM:setCurrent pv 1 2.499000000000000e+01 BO-PS-QF:setCurrent pv 1 2.76000000000000e+00	
B0-PS-0D:setCurrent pv 1 2.29000000000000e+00	
psinjs_setvoltage pv 1 6.80000000000000e+02	
psinjk_setvoltage pv 1 2.00000000000000e+02	
Plain Text 🗸 Tab Width: 8 🗸 Ln 42. Col 54	INS
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Archive System

- Uses BEAUTY (Best Ever Archive Toolset Yet) Archiver
- Integrates with CSS data browser
- > Has ability to specify a time interval
- Show multiple PVs on the same plot
- Uses free PostgreSQL DB
- Installed on a virtual machine with access to EPICS IOCs
- > Only PV reading changes are recorded in the database
- All PVs are monitored currently





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Vacuum readings data browser



Alarm Handler

- Uses BEAST (Best Ever Alarm System Toolkit) Alarm Handler
- Integrates with CSS
- Divides alarms per system
- Alarms can be acknowledged
- Monitors Real-time alarms
- Uses PostgreSQL and Apache ActiveMQ
- Installed on a virtual machine with access to EPICS IOCs
- > ANKA alarm creation server is used

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C2 📾 🛹 🗠	👞 🛸 🔛 🥓		*							
📫 🕕 Alarm	1 1									
Alarm Area Pane										-
		IIII Alarm Table 😂						1		•
		Current Alarms (253)		s	elect					
Microtron	Transfer Line	PV	Description	Alarm Time	Current Sev	Current Stal A	larm Se 🔨	Alarm Statu	Alarm V	alue
		CONTROL-OP0: getL	MINOR alarm: Virtual machine CONTROL-	2014/08/24 15:37:957	OK	ок м		HIGH ALAR		
			MINOR alarm: Virtual machine CONTROL-	2014/09/07 17:50:120	OK	OK M	IINOR	LOW_ALAR		5.94
			MINOR alarm: Virtual machine LAB-WS2 i:		MINOR	LOW_ALARI M		LOW ALAR		
			MINOR alarm: Virtual machine SERVER-RS		OK			HIGH ALAR		
			MINOR alarm: Virtual machine SERVER-RS		OK			HIGH ALAR		
Booster	Infrastructure		MINOR alarm: Virtual machine SERVER-RS		OK			HIGH ALAR		
			MINOR alarm: Virtual machine SERVER-RS	2014/08/26 06:31:679	OK			HIGH ALAR		
			MINOR alarm: Virtual machine SERVICE-W		OK		IINOR	HIGH ALAR		
			MAIOR alarm: Virtual machine CONTROL-	2014/08/26 12:29:794	OK			HIHI ALARM		
		LAB-WS2:getLoad		2014/09/09 15:05:307	OK		AIOR	HIHI ALARN		
Alarm Tree 🕄			MAJOR alarm: Virtual machine SERVER-IS:		OK		AIOR	HIHI ALARN		
ESAME~ 🏓 🤇	D 🐝 🤒 🖌		INVALID alarm: Enable Libera	2014/08/27 09:58:20		Disconnecte IN		Disconnecte		
Area: Microtro	on (INVALID/UDF A		INVALID alarm: Interlock	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte	1	
	Line (INVALID/UDI		INVALID alarm: Interlock	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
	(INVALID/No Conn		INVALID alarm: SA max ADC reading INVALID alarm: Signal conditioning status	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
	ucture (INVALID/Dis									
Area. Initiastri	actore (inviterb/bis	BO-DI-LIB1:SE:CPU	INVALID alarm: CPU usage	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte	-	
		BO-DI-LIB1:SE:FAN1	INVALID alarm: Fan 1 speed error	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
			INVALID alarm: Fan 2 speed error	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
			INVALID alarm: Free memory	2014/08/27 09:58:20	INVALID	Disconnecte I		Disconnecte	L	
			INVALID alarm: Aggregated health	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte	1	
			INVALID alarm: Healthd Silent	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
			INVALID alarm: Temporary file usage	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte		
			INVALID alarm: Motherboard temperature		INVALID	Disconnecte IN		Disconnecte	L	
		BO-DI-LIB1:SE:TEMP	INVALID alarm: RF board temperature	2014/08/27 09:58:20	INVALID	Disconnecte IN		Disconnecte	1	
		Acknowledged Alarms	; (3)							
		PV	Description	Alarm Time	Current Se	V Current Stat	Alarm Se ~	Alarm Stat	L Alarm	i Val
		SERVER-IS1:getFreeP	minor-ack'ed alarm: Virtual machine SERV	2014/08/20 13:23:282	MINOR	LOW_ALARN	minor-ack'	e LOW_ALA	RN 157,2	61,8
		SERVICE-WS2:getFree	minor-ack'ed alarm: Virtual machine SERV	2013/08/20 07:57:423	MINOR	LOW_ALARM	minor-ack'	e LOW_ALA	RF 4,615	,122
		SERVICE-WS2:getFree	minor-ack'ed alarm: Virtual machine SERV	2013/08/20 07:57:423	MINOR	LOW_ALARM	minor-ack'	e LOW_ALA	RM 12,45	1,84
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Future Work

- Continue the work on the control system of the storage ring's power supplies and other subsystems
- Evaluation of a low cost, high performance controllers to be used in the storage ring control system
- Direct control of the timing system EVG and EVR cards by writing a driver for them and run a soft IOC on one of the Linux workstations



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